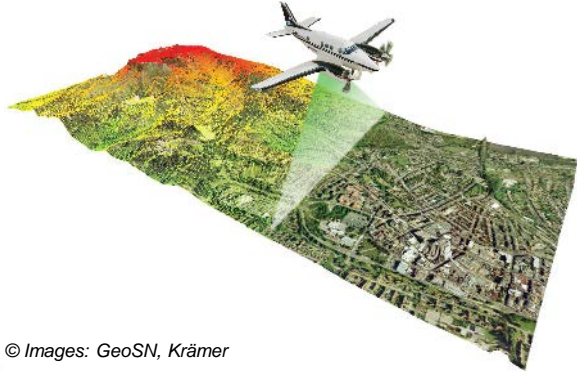




iDiv

Deutsches Zentrum für integrative
Biodiversitätsforschung (iDiv)
Halle-Jena-Leipzig

Multi-sensor approach to monitor the urban landscape – refined mapping of urban structure types and vegetation patterns by means of DOP, LiDAR and UAV data



© Images: GeoSN, Krämer

Roland Krämer (UFZ & iDiv Leipzig) & Ellen Banzhaf (UFZ Leipzig)

Workshop Landschaftsprozessmonitoring mittels Multisensordaten, 29.09.2016, Halle (Saale)



HELMHOLTZ
ZENTRUM FÜR
UMWELTFORSCHUNG
UFZ

The urban landscape – human-induced environment

Quantifying the complex urban environment

- Nature-related, built, social environment
- Social, technical and natural sciences
- Fine scale surveys & data in time and space

Challenges for Remote Sensing (RS)

- High heterogeneity of patterns and processes (high variability – small patches / objects)
- High spatial and temporal dynamics
- Strongly intertwined structures (grey, green, and blue)

→ ***Need for a hybrid RS approach***



Photos: UFZ & Stumpe



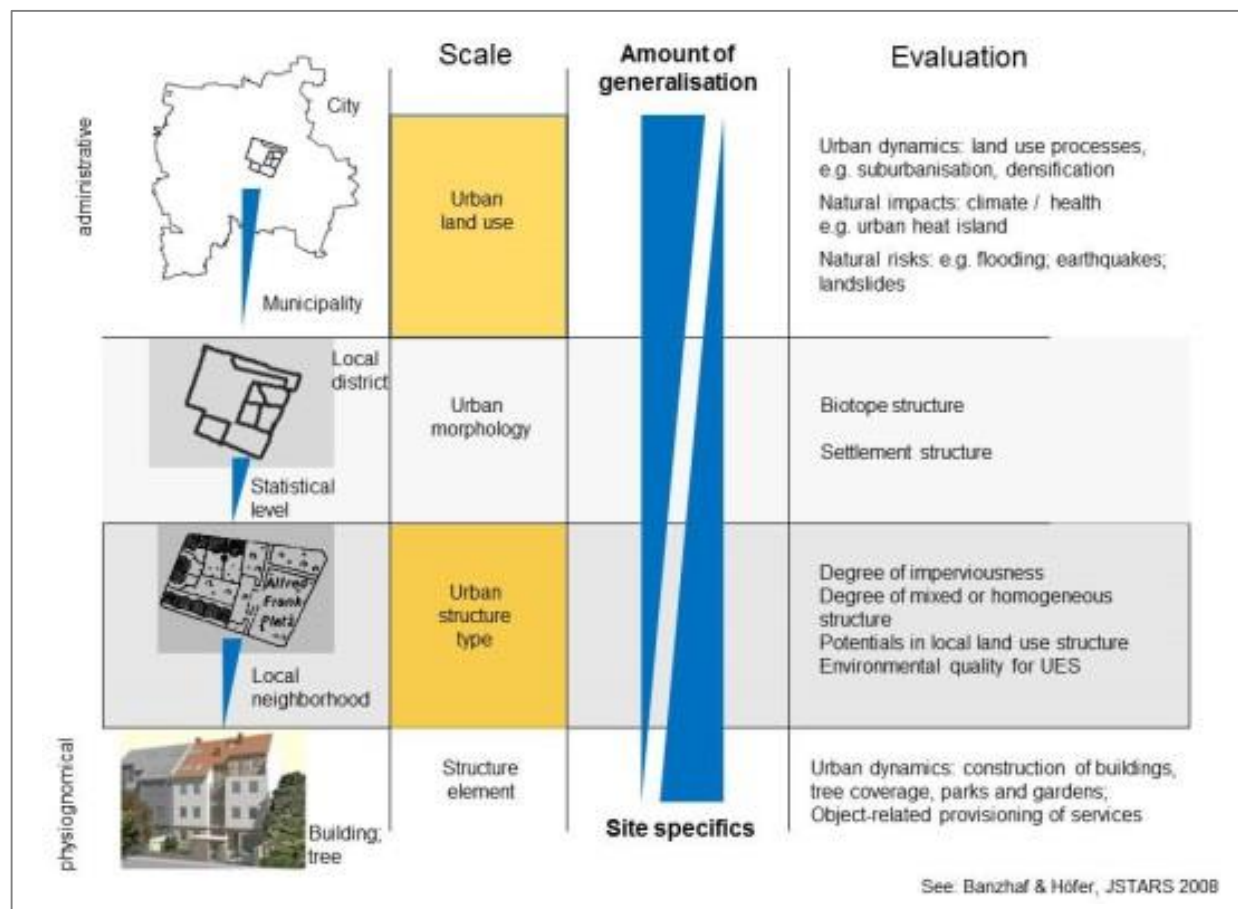
iDiv



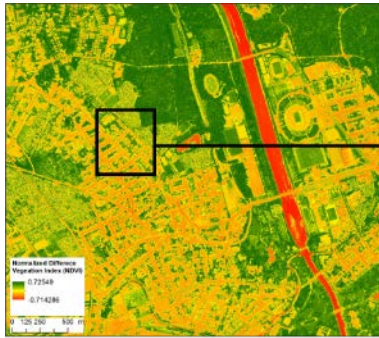
Scale-dependent analysis

- degree of spatial urban information

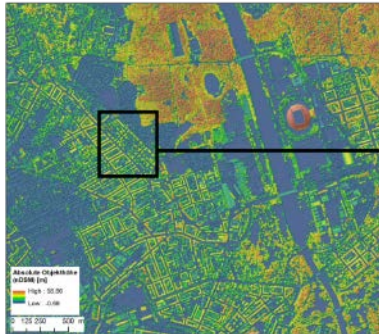
- socio-ecological processes & benefits



Urban tree cover and structure types - Leipzig



Preprocessing incl. NDVI



Preprocessed DOP including absolute height above ground



Material and Methods

- ✓ Digital Orthophotos (DOP) 2012
- ✓ LiDAR derivatives (DEM & DSM) in 2012
 - => three-dimensional model
- ✓ Object-based image analysis techniques (OBIA)

Source: Banzhaf & Kollai 2015, ISPRS, doi:10.5194/isprsarchives-XL-7-W3-301-2015.

Preliminary results from DOP and LiDAR data

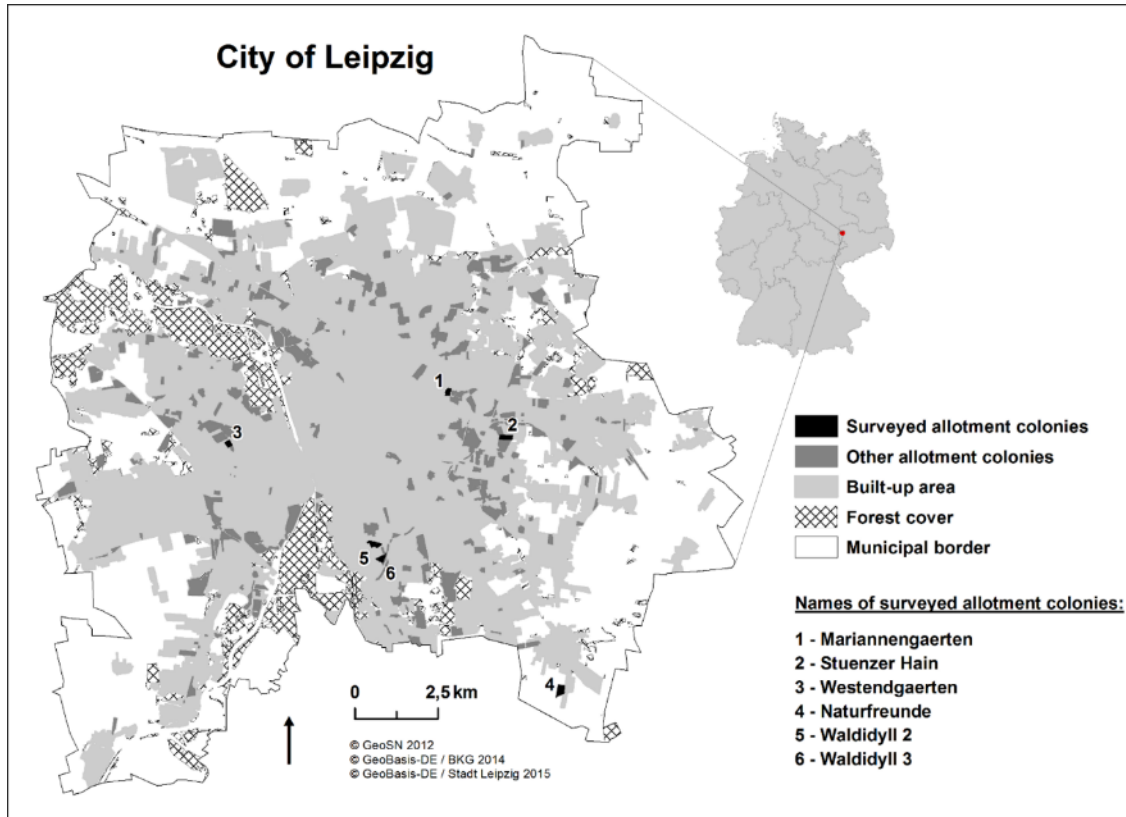
- ✓ Quantifying urban tree cover for the entire city at 60 cm ground resolution
- ✓ Distinguishing mature trees (EEA convention), young trees and bushes, and meadows / lawns
- ✓ Measuring tree cover for different urban districts
- ✓ Structuring residential areas by types of buildings incl. their height to delineate UST
- ❖ Accuracy assessment still to be done!

Next steps – integrating selective VHR+ data



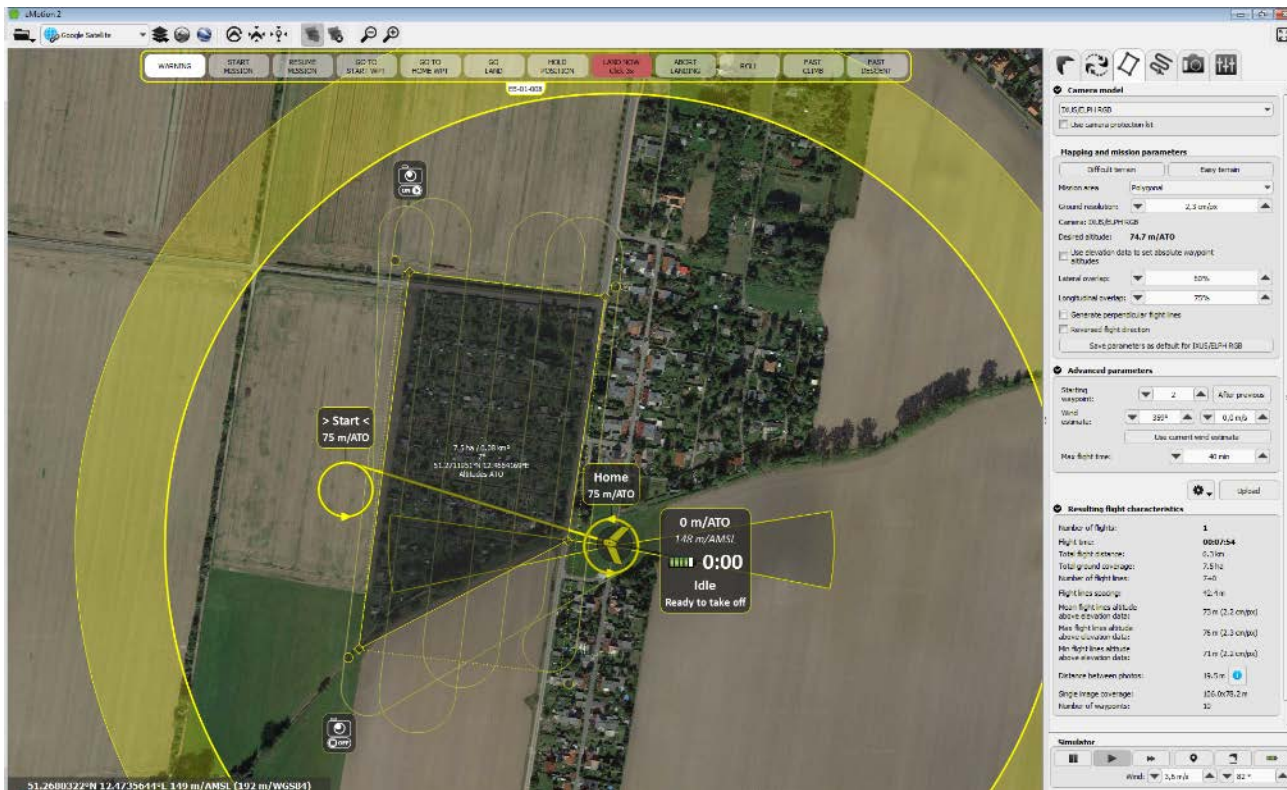
© Krämer / UFZ

Project on Urban Gardens in Leipzig



- 275 allotment colonies (843 ha; 9% of built-up area)
- 15 m² of gardening area per capita
- Colonies' age from 50 – 150 years

Selective, local VHR+ Remote Sensing



„eBee“ drone by Sensefly



- 700 g
- RGB, NIR, MultiSpec
- Max. 1.5 cm GSD/res.
- 40-90 km/h cruise speed
- Max. 45 min. flight
- Post-processing software



Selective, local VHR+ Remote Sensing



© Krämer / UFZ

Selective, local VHR+ Remote Sensing



© Krämer / UFZ

Selective, local VHR+ Remote Sensing

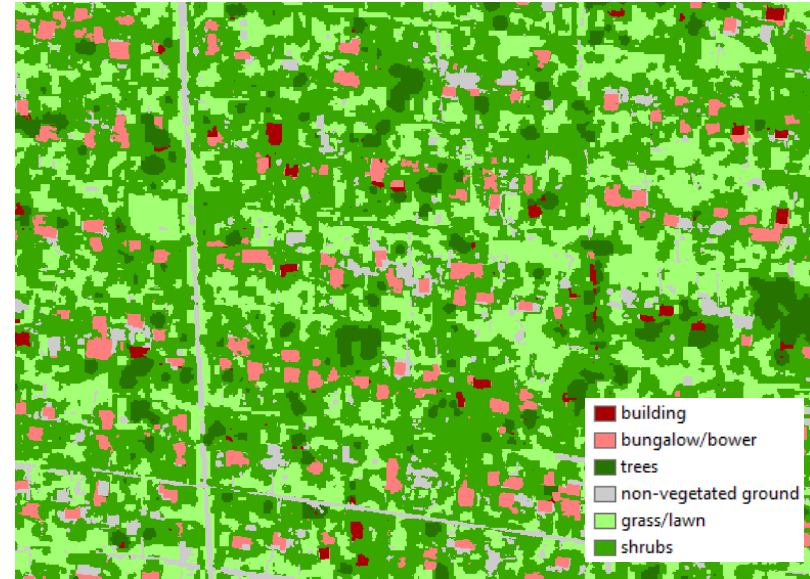


Outlook: Integrating remote sensing data → improving all products

UAV data/products (selective)



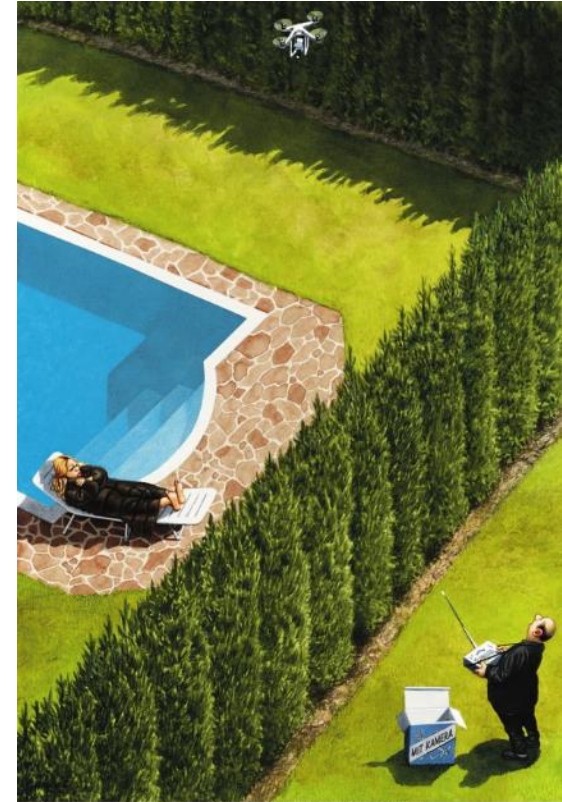
Airborne products (DOP & LiDAR),
spatially explicit



© Kraemer & Banzhaf / UFZ

Outlook / Final remarks

- Joining and calibrating **hybrid remote sensing** data needed for urban areas but **challenging**
- **Remote sensing** alone **not sufficient** in coupled natural-built-social system (only a proxy for land-use)
- **Interdisciplinarity** needed: social surveys, (mobile) sensors, environmental (point) data, biological surveys, statistics
- Scientific UAV application still needs big effort (and public acceptance)



SPHILZEUS FÜR NIEDRIGE MACHERN: DIE SPIONAGE-DRONE ZUM SELBERBESTELN

© Haderer

Thank you

roland.krämer@idiv.de
ellen.banzhaf@ufz.de



Photos: Stumpe, Krämer